



EtherCAT® in Test Systems

An Experience Report

EtherCAT in Mobile Applications
Frankfurt, 2013-02-06

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Agenda

> **Vector – A Very Short Introduction**

VT System

Why EtherCAT?

Experience

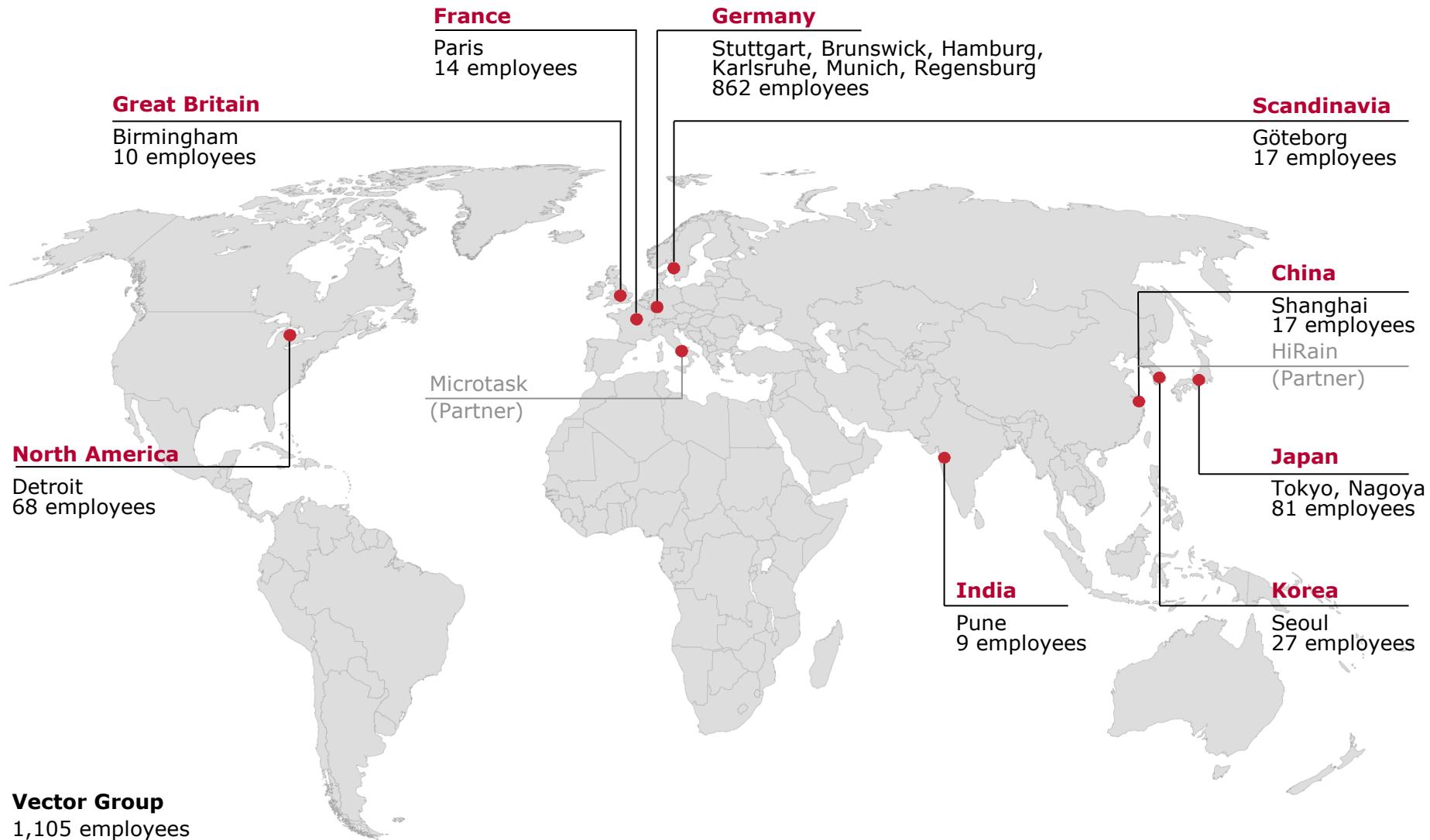


Vector – A Very Short Introduction

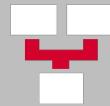


**Vector provides OEMs and suppliers
of automotive and related industries
a professional and open development platform of
tools, software components and services
for creating embedded systems.**

Vector Worldwide



Vector Application Areas



Development of Distributed Systems

PREEvision, Network Designer, ...



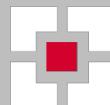
ECU Software

MICROSAR, Customer Services, ...



ECU Testing

CANoe, VT System, Logger, ...



Diagnostics

CANdela, ODXStudio, ...



ECU Calibration

CANape, VX1000, vCDM, ...



Process Management and Development

Consulting Services

Supported Markets (Non Passenger Cars)



Truck/Trailer Application



Special Vehicles



Buses



Agriculture Electronics



Railway Electronics



Aerospace



Medical Systems



Wind Turbines

Other Industries

- Manufacturer of sensors/actuators for bus systems
- Building automation
- Networking in ship building
- Networking in construction machines

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Vector – A Very Short Introduction

> **VT System**

Why EtherCAT?

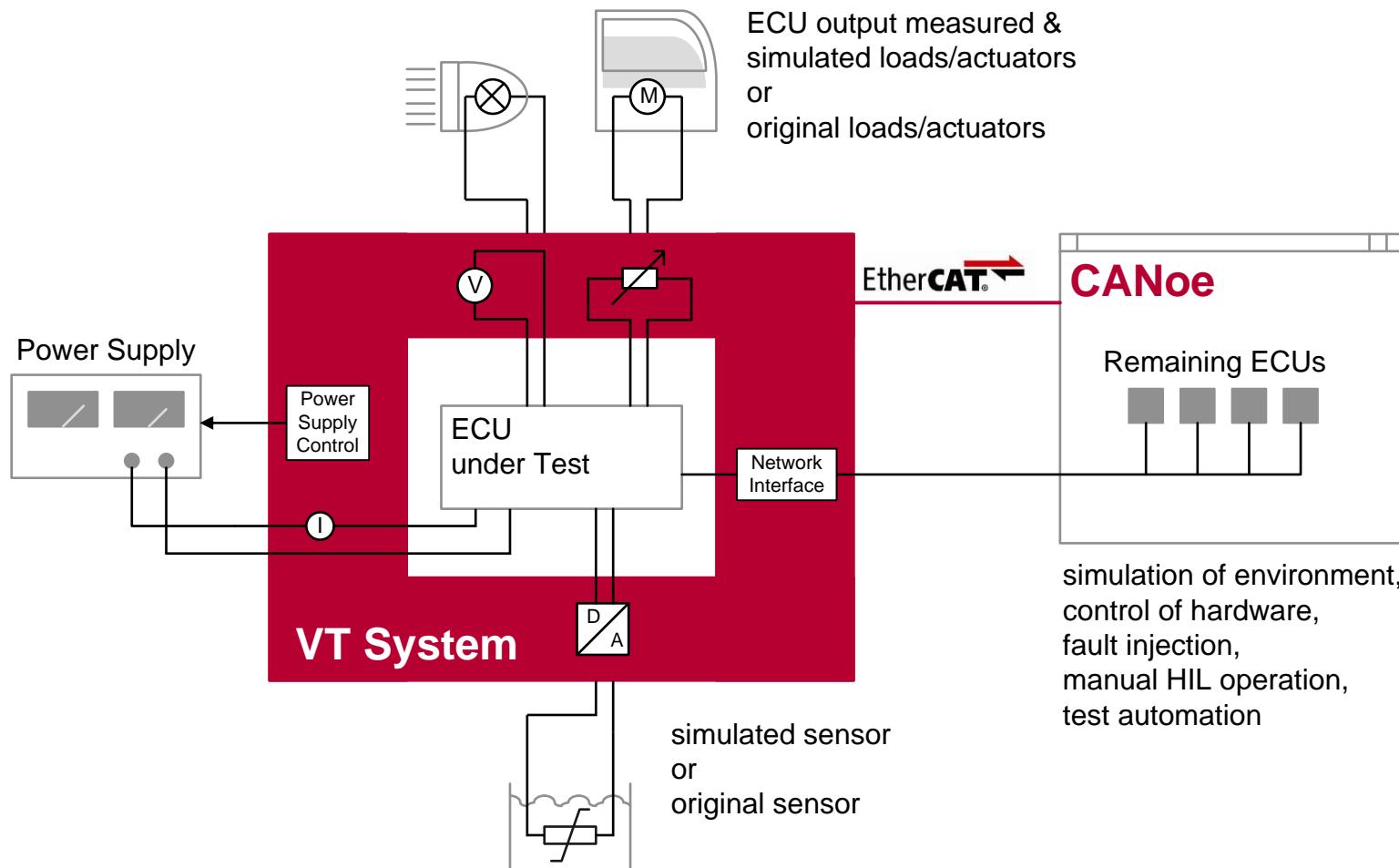
Experience

VT System is a modular **test system** for functional tests of **automotive ECUs** with CANoe.

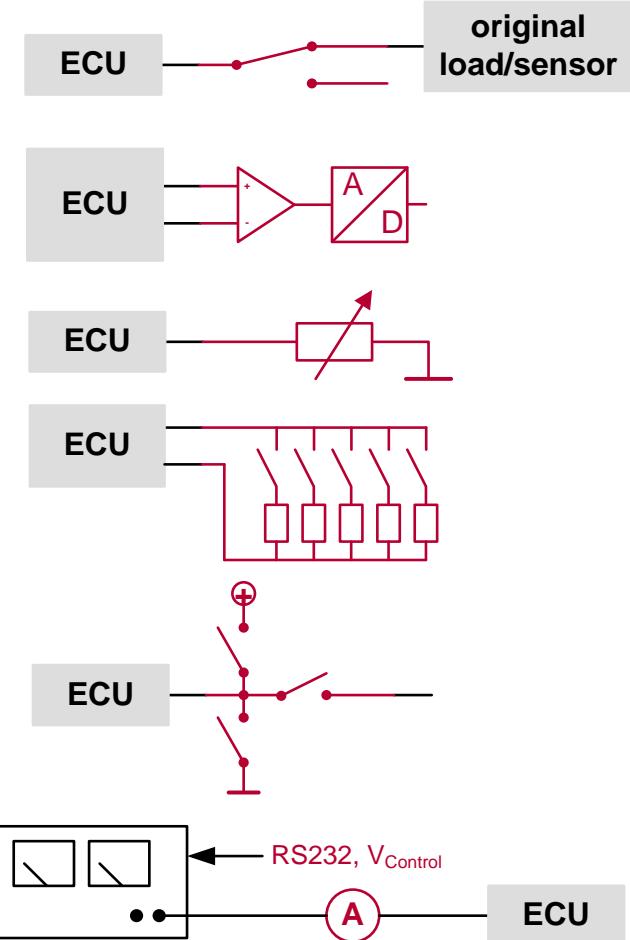


VT System

Integrated ECU Test Hardware



- ▶ **Switching** the signal path, e.g. to the original load or sensor
- ▶ **Measurement** of ECU output signals, including differential signals, average values, RMS, PWM parameters
- ▶ **Simulation of loads**
- ▶ **Stimulation of sensor** inputs (sensor simulation), including arbitrary signal generation and PWM output
- ▶ **Fault injection**, e.g. short circuits to ground or V_{bat} , short-circuits between ECU lines, broken wires
- ▶ **Control of supply power**, definition of input voltage and measurement of power consumption



- ▶ Independent I/O modules for 19" racks
 - ▶ Each module handles several ECU inputs or outputs (e.g. a temperature sensor input or a lamp output)
 - ▶ Type and number of modules may be configured individually
 - ▶ Individual assemblies from small boxes to complete test racks



- ▶ VT modules and PC connected over Ethernet
 - ▶ Industrial Ethernet protocol EtherCAT used
 - ▶ Racks can be cascaded
 - ▶ Modules are interconnected using a small backplane with EtherCAT on LVDS (E-Bus)

EtherCAT®

Agenda

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VT System

> Why EtherCAT?

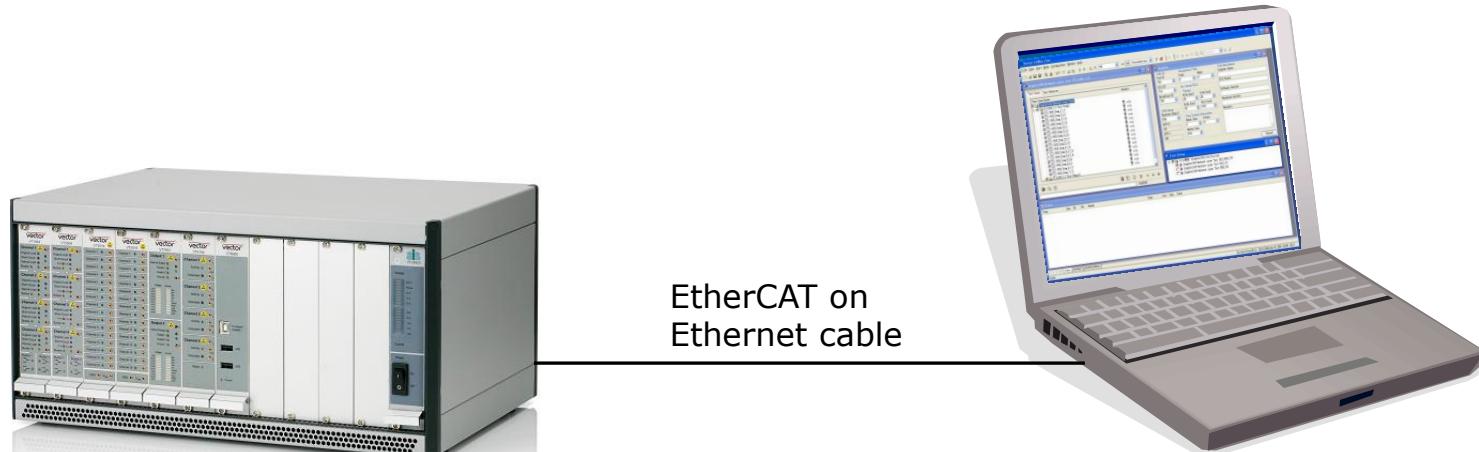
Experience

- ▶ The connection between **I/O hardware** (VT System) and **test control software** (CANoe on the PC) has to be
 - ▶ Real-time = defined round-trip time
 - ▶ Fast
 - ▶ Low Latency
 - ▶ Reliable = system is switched off when connection is broken

Why EtherCAT?

PC Interface

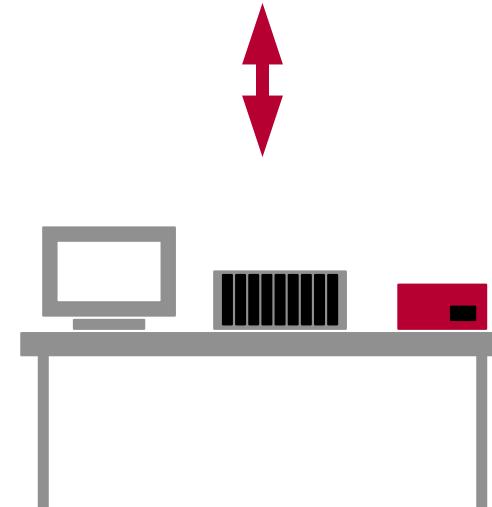
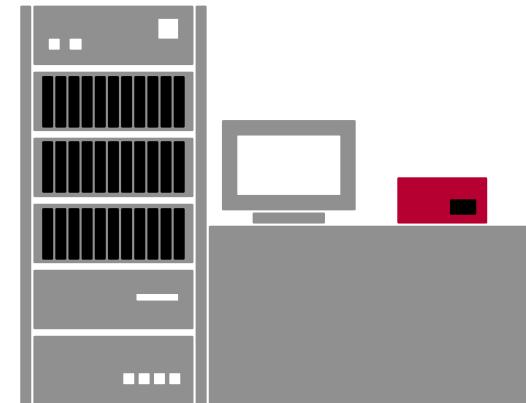
- ▶ Using the standard Ethernet port on host PC
 - ▶ No specific host interface needed
 - ▶ No specific low-level drivers needed
 - ▶ Ethernet port available on all kinds of computing platforms (rack PC, desktops, notebooks, embedded PCs, COM boards, ...)
 - ▶ VT System may be used temporarily (e.g. by notebooks)



Why EtherCAT?

Scalability

- ▶ Several kinds of test systems possible:
 - ▶ Small test boxes on developer's desk
 - ▶ Universal I/O hardware
 - ▶ Comprehensive ECU tester
 - ▶ HIL systems
- ▶ Racks can be cascaded
- ▶ Even test systems can be cascaded

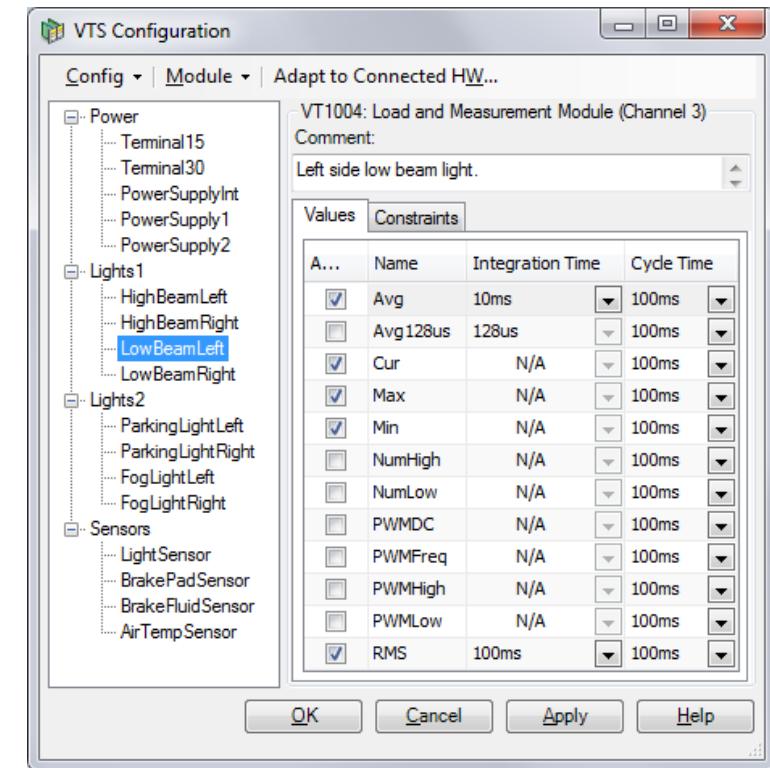


Why EtherCAT?

Automatic Configuration

- ▶ Automatic system detection
 - ▶ Only Ethernet interface has to be selected by the user
- ▶ Automatic module detection
- ▶ Easy configuration in CANoe
 - ▶ Selecting measurement values
 - ▶ Defining names of channels

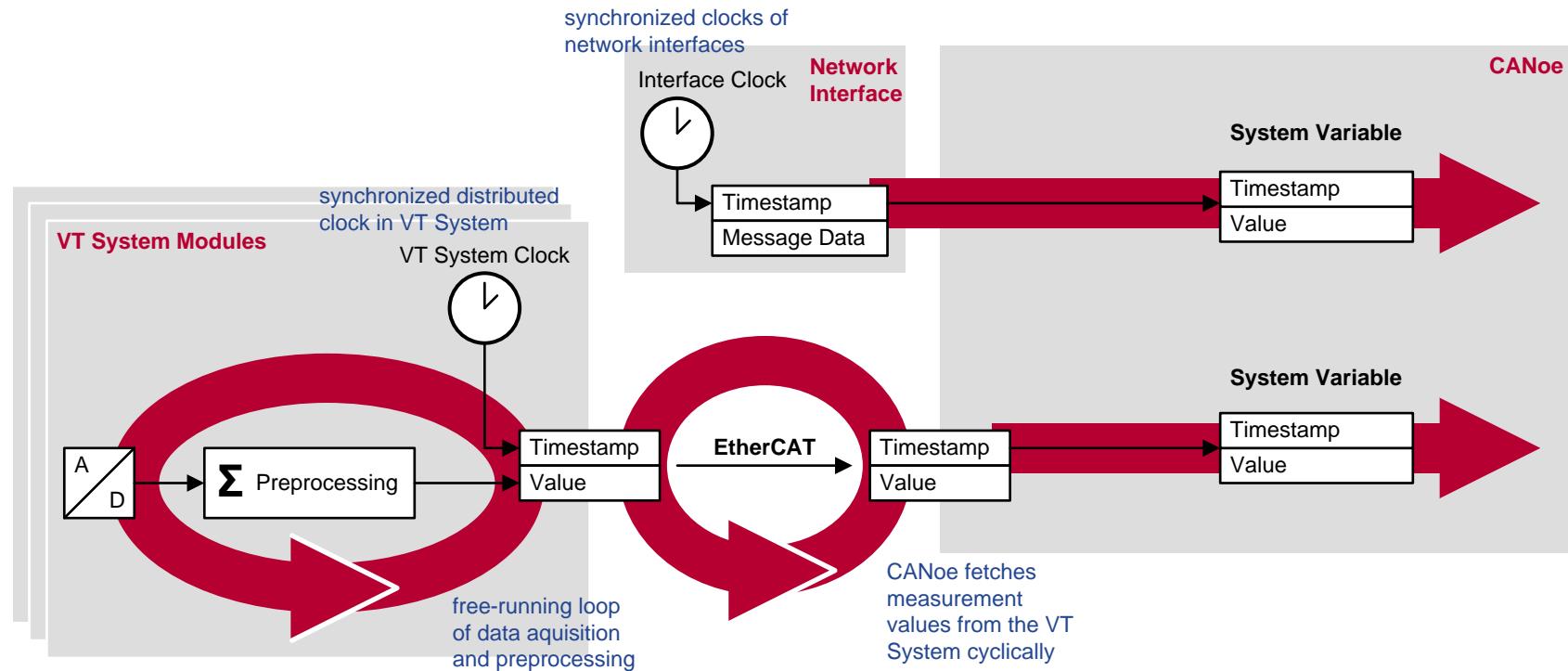
→ Comfort for usage, not really necessary for operation



Why EtherCAT?

Decoupling of Module and Host Operation

- ▶ Free-running operation of I/O modules
- ▶ Synchronized clocks on VT System
- ▶ Time-sync within VT System and with host system (incl. other network interfaces)



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> Experience

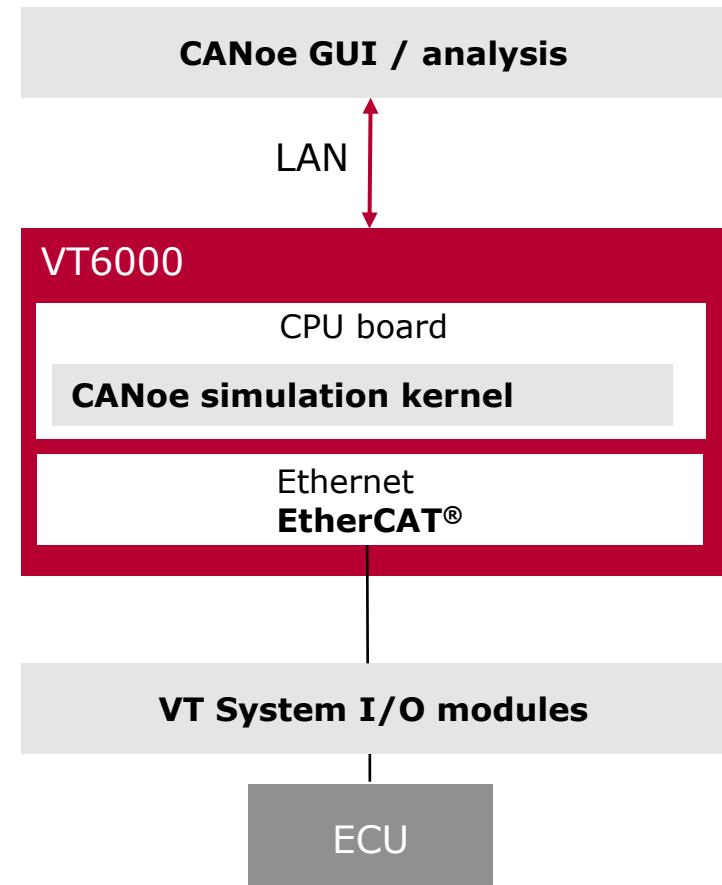
Experience

EtherCAT on the Host PC

- +
- No problem with all kinds of Ethernet hardware
 - ▶ Even USB/EtherCAT adapters will work – but not very well (bad latency)
- +
- Almost no network configuration needed
- +
- No security issues (virus ...)
 - ▶ EtherCAT ≠ IP
-
- Sometimes trouble with firewall software on customer PCs
-
- Sometimes problems are hard to find
 - ▶ E.g. if the company network is used
(of course, it's the fault of the user, but it works perfectly unless a second ...)

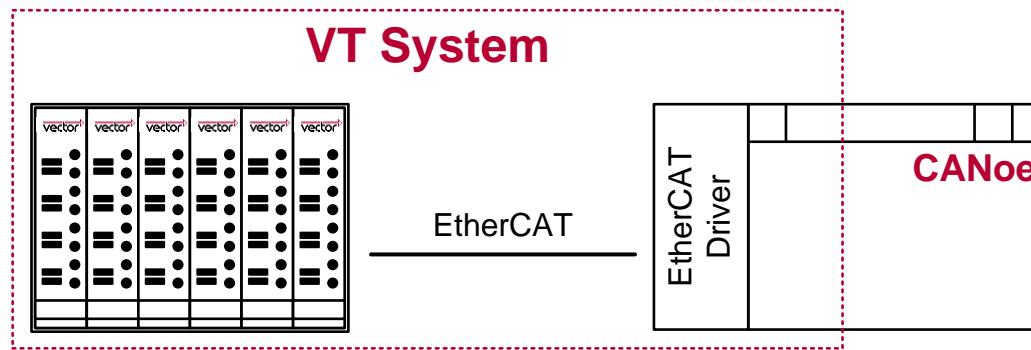
- ▶ EtherCAT is proven to be fast, real-time, and reliable
- ▶ Timing of PC application (EtherCAT driver) is critical
 - ▶ Accuracy of EtherCAT send timers determines the overall accuracy
 - ▶ Therefore we introduced timestamps for measurement purposes
- ▶ Streaming of large data blobs is not the strength of EtherCAT, but sometimes necessary ...
 - ▶ Download of configuration data to modules
 - ▶ Upload of recorded data from module to PC
- ▶ For streaming of event based data (e.g. CAN messages) we use a parallel data path (PCI Express on cable)

- ▶ What will we do if more reliable operation is needed?
- ▶ Real-time module within VT System
 - ▶ Embedded PC based on COM module
 - ▶ GUI PC connected by LAN
 - ▶ Dedicated EtherCAT interface for controlling the I/O modules
- EtherCAT can also be used successfully in this high-performance system



- +
- Straightforward HW design based on EtherCAT ASIC
- +
- Needed firmware is not very complex
 - ▶ EtherCAT state machine mainly handled by ASIC
-
- Throughput of µC interface is limited
 - ▶ Measurement value update rate limited in some applications (using a FPGA and a very high number of measurement values)

- ▶ VT System consists of
 - ▶ VT Hardware with FPGA/firmware
 - ▶ Software functions on the host PC



- ▶ EtherCAT is used for real-time communication

EtherCAT can successfully be used for a specific application like the VT System!

Thank you for your attention.

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Vector Informatik GmbH